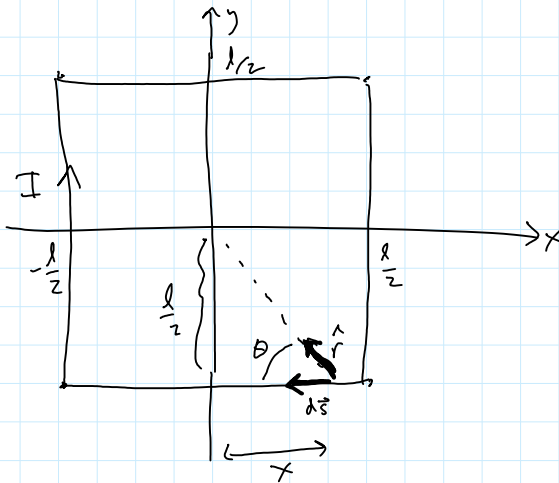


Goals for the Lecture:

- 1) Be able to calculate inductance and EMF generated across an inductor
- 2) Understand that RL circuits are very similar to RC circuits
- 3) Be able to solve problems involving time constants for RL circuits
- 4) Be able to calculate energy stored in the magnetic field of an inductor

Review: Book Probs 30-5



$$B = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s} \times \hat{r}}{r^2}$$

$$d\vec{s} \times \hat{r} = ds (i) \sin\theta$$

$$\sin\theta = \frac{l/2}{r} = \frac{l}{2\sqrt{x^2 + (l/2)^2}}$$

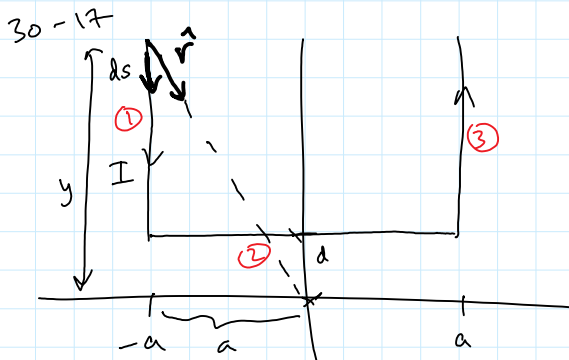
$$r = \sqrt{x^2 + (l/2)^2}$$

$$B = \frac{8\mu_0 I}{4\pi} \int_0^{l/2} \frac{l}{2} \frac{dx}{[x^2 + (l/2)^2]^{3/2}}$$

$$= \frac{8\mu_0 I}{4\pi} \frac{l}{2} \left. \frac{x}{(\frac{l}{2})^2 \sqrt{x^2 + (\frac{l}{2})^2}} \right|_0^{l/2}$$

$$\frac{l/2}{(\frac{l}{2})^2 \sqrt{2} \frac{l}{2}}$$

$$= \frac{2\mu_0 I}{\pi\sqrt{2}} \frac{2}{l} = \frac{2\sqrt{2}\mu_0 I}{l\pi}$$



$$\vec{B}_{total} = \vec{B}_1 + \vec{B}_2 + \vec{B}_3$$

↑ out of page ↑ into page ↑ out of page

$$B_1 = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s} \times \hat{r}}{r^2}$$

$$d\vec{s} \times \hat{r} = dy (1) \sin\theta$$

$$= dy \frac{a}{r}$$

$$r = \sqrt{y^2 + a^2}$$

$$= \frac{\mu_0 I}{4\pi} \int_d^\infty \frac{a dy}{[y^2 + a^2]^{3/2}}$$

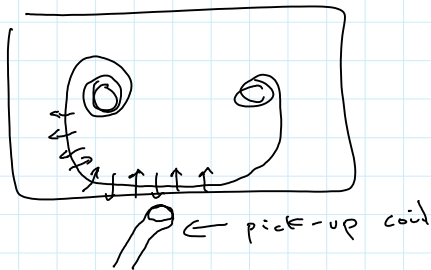
$$= \frac{\mu_0 I a}{4\pi} \frac{y}{a^2 \sqrt{y^2 + a^2}} \Big|_d^\infty$$

$$\frac{1}{a^2 \sqrt{\frac{y^2}{a^2} + \frac{a^2}{y^2}}} \Big|_d^\infty$$

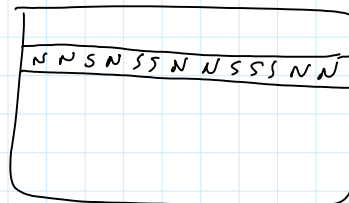
$$= \frac{\mu_0 I a}{4\pi} \left(\frac{1}{a^2} - \frac{d}{a^2 \sqrt{d^2 + a^2}} \right)$$

Applications -

Cassette tape



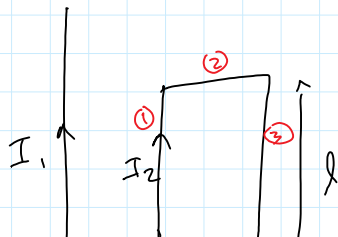
Credit card



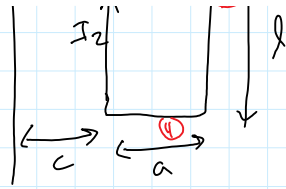
Speakers

Microphones

30-25



Find the Force on each side of the loop
direction of Forces:



direction of Forces:

$$F_1 \leftarrow$$

$$F_2 \uparrow$$

$$F_3 \rightarrow$$

$$F_4 \downarrow$$

F_2 and F_4 will cancel

$$\vec{F}_2 = -\vec{F}_4$$

But, $F_1 > F_3$ so the net force is to the left

Let's find F_1 :

1st find B from I_1 at the location of side ①

$$\int \vec{B} \cdot d\vec{s} = \mu_0 I_1$$

$$B 2\pi r = \mu_0 I_1$$

$$B = \frac{\mu_0 I_1}{2\pi r}$$

at $r = c$

$$B_1 = \frac{\mu_0 I_1}{2\pi c}$$

$$\vec{F} = I \vec{L} \times \vec{B}$$

$$F_1 = I_2 l B_1$$

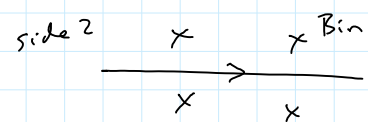
$$F_1 = I_2 l \frac{\mu_0 I_1}{2\pi c} \leftarrow$$

Find F_2 :

$$B = \frac{\mu_0 I_1}{2\pi r}$$

$$\vec{F} = I \vec{L} \times \vec{B}$$

$$F_2 = I l_1 \times R \leftarrow$$



$$\theta = 90^\circ$$

$$\sin \theta = 1$$

$$F = I L \times B$$

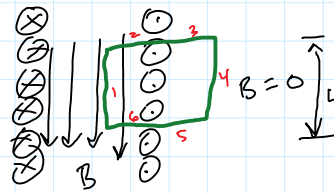
$$\int dF = \int I dL \times B \quad \leftarrow \sin \theta = 1$$

$$F = I_2 \int_c^{a+c} dr \frac{\mu_0 I_1}{2\pi r}$$

$$= \frac{\mu_0 I_1 I_2}{2\pi} \ln\left(\frac{a+c}{c}\right)$$

Ideal Solenoid

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{in}$$



$$\int_1 \vec{B} \cdot d\vec{s} + \int_2 \vec{B} \cdot d\vec{s} + \int_3 \vec{B} \cdot d\vec{s} + \int_4 \vec{B} \cdot d\vec{s} + \int_5 \vec{B} \cdot d\vec{s} + \int_6 \vec{B} \cdot d\vec{s} = \mu_0 I_{in}$$

$\underbrace{BL}_{BL} + \underbrace{0}_{\vec{B} \cdot d\vec{s} = 0, \vec{B} \perp d\vec{s}} + \underbrace{0}_{\text{because } B=0} + \underbrace{0}_{\text{because } B=0} + \underbrace{0}_{\text{because } B=0} + \underbrace{0}_{\vec{B} \cdot d\vec{s} = 0, \vec{B} \perp d\vec{s}} = \mu_0 I_{in}$

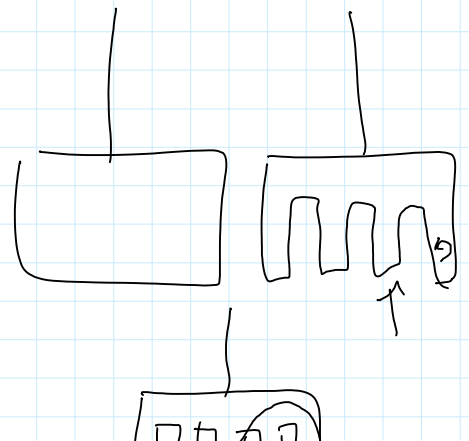
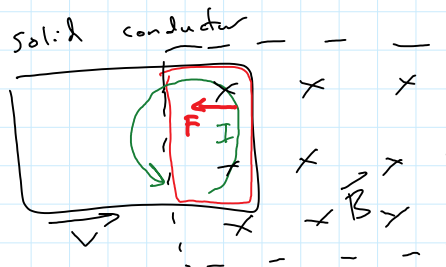
$$BL = \mu_0 I_{in}$$

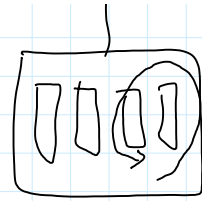
$$BL = \mu_0 N I$$

$$B = \mu_0 \frac{N}{L} I$$

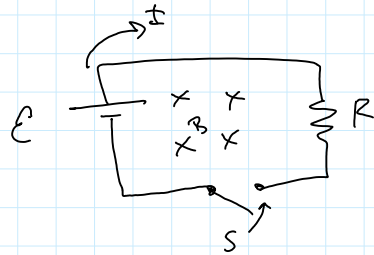
$$B = \mu_0 n I$$

$$\uparrow n = \frac{N}{L}$$





Inductance



- 1) close switch
- 2) current begins to flow
- 3) current creates a magnetic field (increasing magnetic flux into the page)
- 4) Increasing flux creates an EMF (or current) in the opposite direction (back EMF)

or
Self-induction

Self-induced EMF:

$$\mathcal{E}_L = -N \frac{d\Phi_B}{dt}$$

for a solenoid:

$$B = \mu_0 n I \quad \text{ideal solenoid}$$

$$\Phi_B = BA = \mu_0 n I A$$

$$\mathcal{E}_L = -N \mu_0 n A \frac{dI}{dt} \quad \left(\propto \frac{I}{I} \right)$$

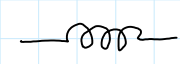
$$= -N \frac{\Phi_B}{I} \frac{dI}{dt}$$

$$= -L \frac{dI}{dt}$$

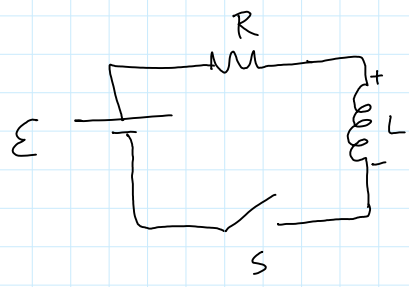
N \Phi \quad \text{Inductance}

$$\text{For an ideal Solenoid: } L = \frac{N \Phi}{I} \quad \text{Inductance}$$

units for inductance: Henry $H = \frac{Vs}{A}$

Inductor: symbol: 
 typically a large coil - like a solenoid
 always opposes the change in current

RL Circuits



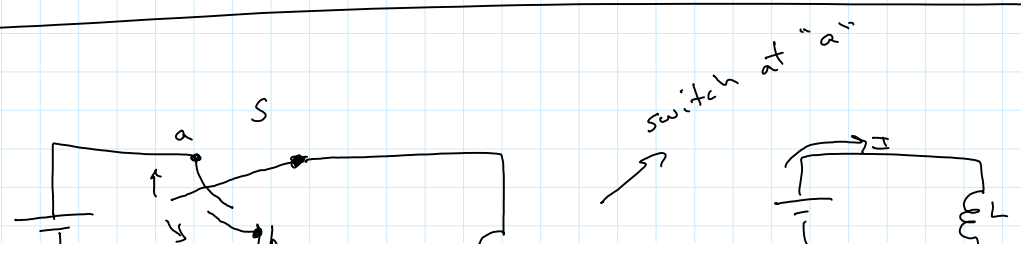
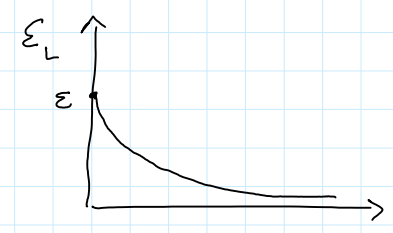
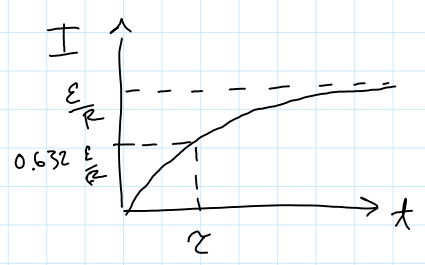
close switch at $t=0$
 $\mathcal{E}_L = -L \frac{dI}{dt}$

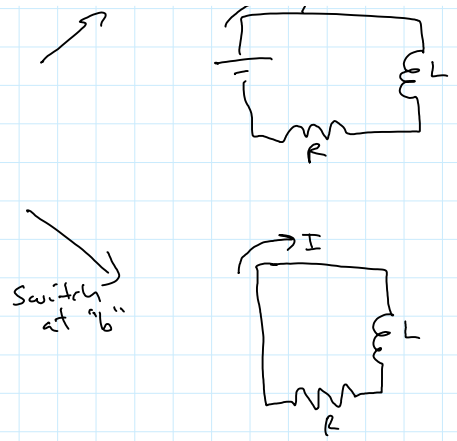
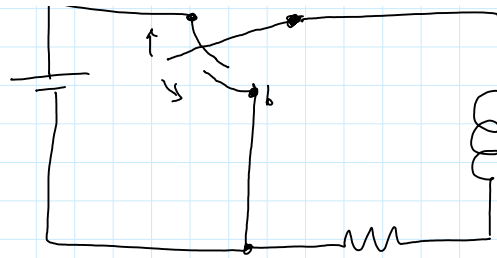
Loop Rule:

$$\mathcal{E} - IR - L \frac{dI}{dt} = 0$$

$$I = \frac{\mathcal{E}}{R} \left(1 - e^{-\frac{t}{\tau}} \right)$$

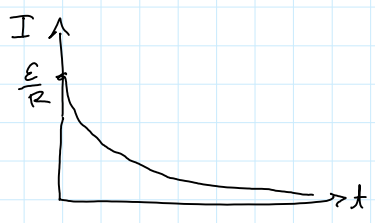
$\tau = \text{time constant} = \frac{L}{R}$



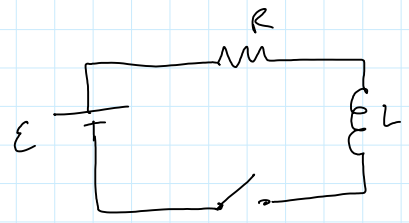


Switch at "b"

$$I = \frac{\mathcal{E}}{R} e^{-\frac{t}{\tau}}$$



Energy in the magnetic field:



Loop rule:

$$\mathcal{E} = IR + L \frac{dI}{dt}$$

Multiply by I:

$$I\mathcal{E} = I^2R + LI \frac{dI}{dt}$$

(Red arrows point from the terms to their meanings:
 - $I\mathcal{E}$ is labeled "Power supplied by battery"
 - I^2R is labeled "Power delivered to resistor"
 - $LI \frac{dI}{dt}$ is labeled "must be power stored in inductor")

$U =$ energy stored in inductor

$$\frac{dU}{dt} = \text{Power}$$

$$\frac{dU}{dt} = LI \frac{dI}{dt}$$

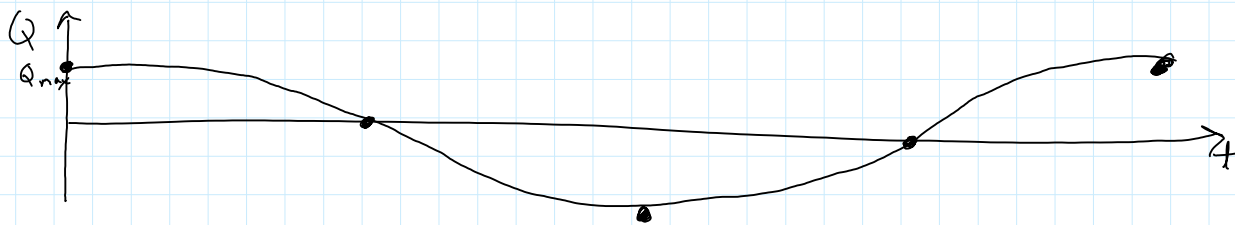
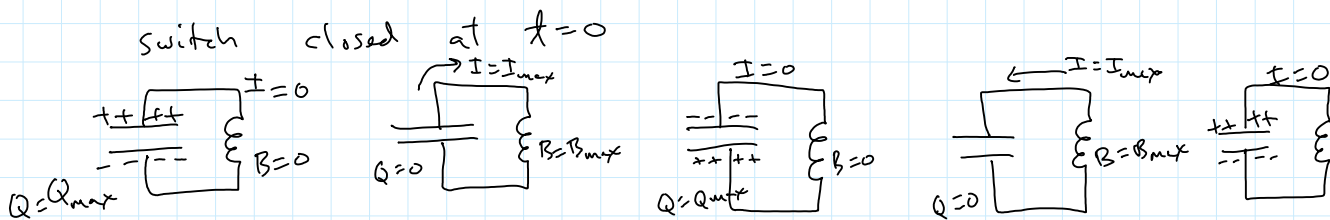
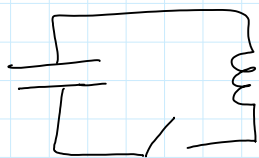
$$U = \frac{1}{2} LI^2 \quad \text{energy stored in inductor}$$

Inductor \rightarrow stores energy in magnetic field

capacitor \rightarrow " " " electric "

$$U = \frac{1}{2} CV^2 \quad \text{energy stored in capacitor}$$

LC circuit



$$\frac{d^2 Q}{dt^2} = -\frac{1}{LC} Q$$

$$Q = Q_{max} \cos(\omega t + \phi)$$

$$F = ma$$

$$-kx = m \frac{d^2 x}{dt^2}$$

$$Q = Q_{\max} \cos(\omega t + \psi)$$

↑
sets
initial
condition

$$\omega = \frac{1}{\sqrt{LC}}$$

angular
freq of
oscillation
in an LC circuit

