## Goals for the Lecture:

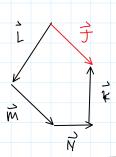
1) Be able to solve 1-D kinematics problems (constant acceleration) using the equations and a graphical approach

2) Review vector addition

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|      | P   | -   |    |
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$$\vec{B} = \vec{P} + \vec{Q} + \vec{R}$$





|          |           |       | COMPONENIS |                            |                            |                   |                            |                                     |                                     |
|----------|-----------|-------|------------|----------------------------|----------------------------|-------------------|----------------------------|-------------------------------------|-------------------------------------|
|          | ١         | >     | ۷          | . I                        |                            | 2                 | )                          |                                     |                                     |
| Ā        |           | _     | -2         |                            |                            | 7                 | >                          |                                     |                                     |
| _<br>B   |           |       | 2          |                            |                            |                   | ک                          |                                     |                                     |
| _        |           |       | - (        |                            |                            | C                 | >                          |                                     |                                     |
| _<br>[.  | >         |       | 3          |                            |                            | (                 |                            |                                     |                                     |
| <u> </u> |           | _2    | - +2       | -1+3                       | \<br>\                     | 3- <sup>-</sup>   | 2 J                        | 0 +                                 | (                                   |
|          | B - C - I | B C D | A - B      | A -2<br>B 2<br>C -1<br>D 3 | A -2<br>B 2<br>C -1<br>D 3 | A -2 B 2 C -1 D 3 | A -2 3<br>B 2 -3<br>C -1 C | A - 2 3 $B 2 - 2$ $C - 1 0$ $D 3 1$ | A -2 3<br>B 2 -2<br>C -1 0<br>D 3 1 |

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|---------|--|
|         | X comp / y comp  |
|         | A (100 c.s 30° 100 sin 30°                                 |
|         | B 0 - 150  |
|         | 1 - 200 cos 20° - 200 sin 20°  1 - 100 sin 30° 100 cos 30° |
|         |  |
| R = A+8 | 1-(+P) Ax+Bx+Cx+Dy Ay+By+Cy+Dy                             |

